

# IMPULSE AND MOMENTUM



## IMPULSE

Impulse of a force 'F' acting on a body for a time interval  $t = t_1$  to  $t = t_2$  is defined as

$$\vec{I} = \int_{t_1}^{t_2} \vec{F} dt$$

$$\vec{I}_{Re} = \int_{t_1}^{t_2} \vec{F}_{Res} dt = \Delta \vec{P}$$

(Impulse - Momentum Theorem)

## COEFFICIENT OF RESTITUTION (e)

The coefficient of restitution is defined as the ratio of the impulses of reformation and deformation of either body.

$$e = \frac{\text{Impulse of reformation}}{\text{Impulse of deformation}} = \frac{\int F_r dt}{\int F_d dt}$$

$$e = \frac{\text{Velocity of separation of point of contact}}{\text{Velocity of approach of point of contact}}$$

## LINEAR MOMENTUM

Linear momentum is a vector quantity defined as the product of an object's mass  $m$ , and its velocity  $v$ . Linear momentum is denoted by the letter  $p$  and is called "momentum" in short:

$$p = mv$$

Note that a body's momentum is always in the same direction as its velocity vector. The units of momentum are  $\text{kg}\cdot\text{m/s}$ .

## CONSERVATION OF LINEAR MOMENTUM

For a single mass or single body, If net force acting on the body is zero. Then,

$$\vec{p} = \text{constant} \quad \text{or} \quad \vec{v} = \text{constant}$$

(if mass = constant)

If net external force acting on a system of particles or system of rigid bodies is zero. Then,

$$\vec{P}_{CM} = \text{constant} \quad \text{or} \quad \vec{V}_{CM} = \text{constant}$$



# COLLISION



Note :- In every type of collision, only linear momentum remains constant.

## HEAD ON ELASTIC COLLISION



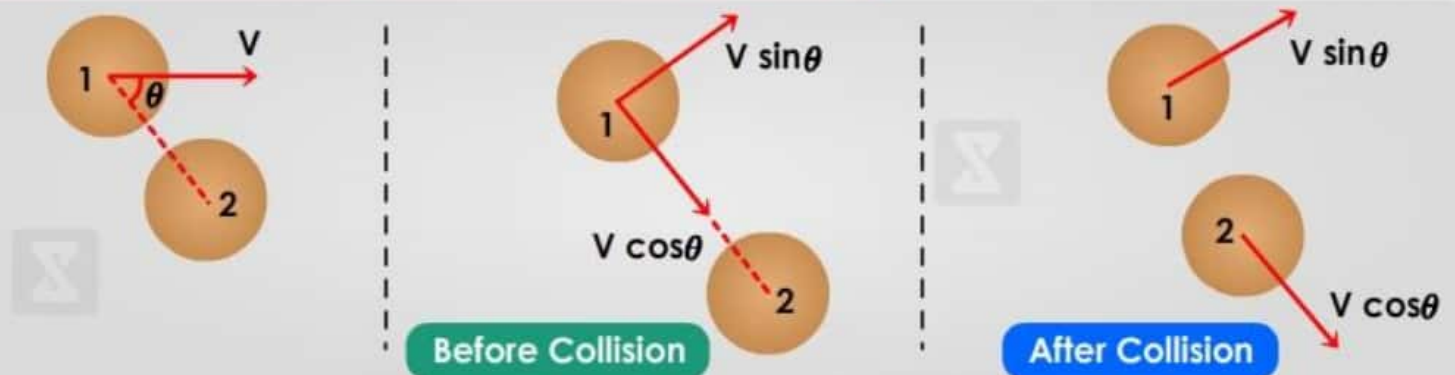
In this case, linear momentum and kinetic energy both are conserved. After solving two conservation equations. We get,

$$v'_1 = \left( \frac{m_1 - m_2}{m_1 + m_2} \right) v_1 + \left( \frac{2m_2}{m_1 + m_2} \right) v_2 \quad \text{and} \quad v'_2 = \left( \frac{m_2 - m_1}{m_1 + m_2} \right) v_2 + \left( \frac{2m_1}{m_1 + m_2} \right) v_1$$

## HEAD ON INELASTIC COLLISION

- ➔ In an inelastic collision, the colliding particles do not regain their shape and size completely after the collision.
- ➔ Some fraction of mechanical energy is retained by the colliding particles in the form of deformation potential energy. Thus, the kinetic energy of the particles no longer remains conserved.
- ➔ (Energy loss)<sub>Perfectly Inelastic</sub> > (Energy loss)<sub>Partial Inelastic</sub>
- ➔  $0 < e < 1$  :  $e$  = coefficient of restitution

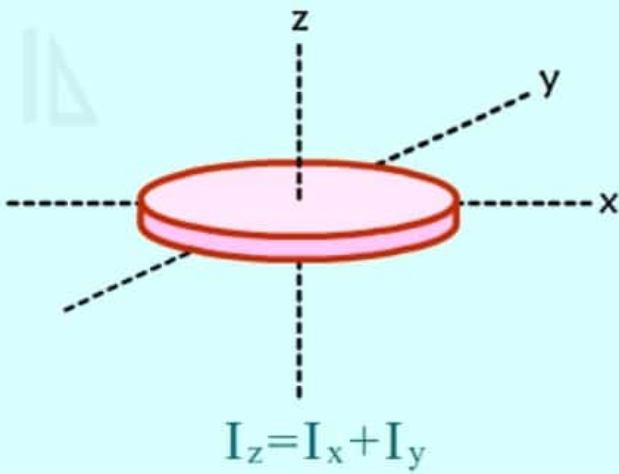
## OBLIQUE COLLISION (BOTH ELASTIC IN ELASTIC)



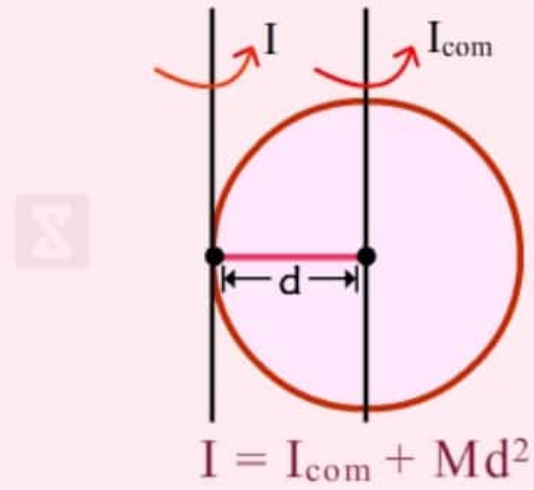
BALL	COMPONENT ALONG COMMON TANGENT DIRECTION		COMPONENT ALONG COMMON NORMAL DIRECTION	
	Before Collision	After Collision	Before Collision	After Collision
1	$V \sin \theta$	$V \sin \theta$	$V \cos \theta$	0
2	0	0	0	$V \cos \theta$



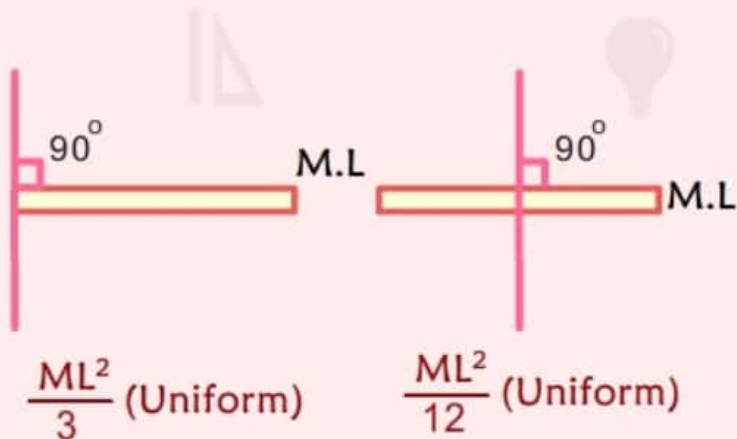
## Perpendicular Axis Theorem



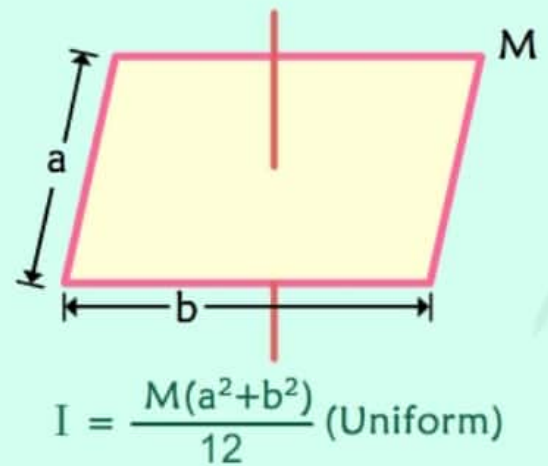
## Parallel Axis Theorem



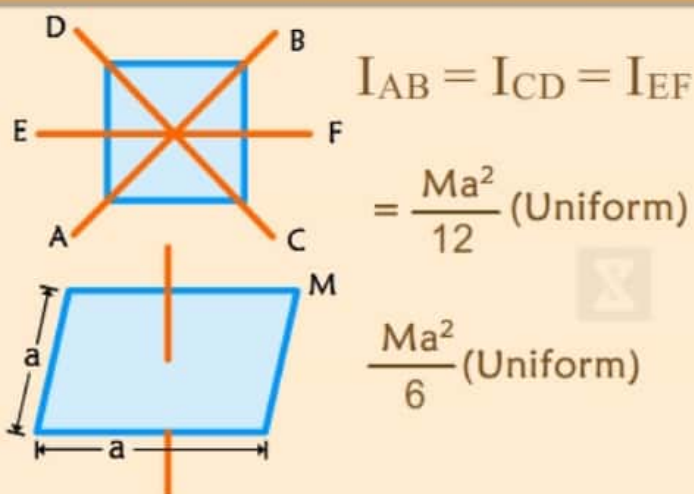
## Rod



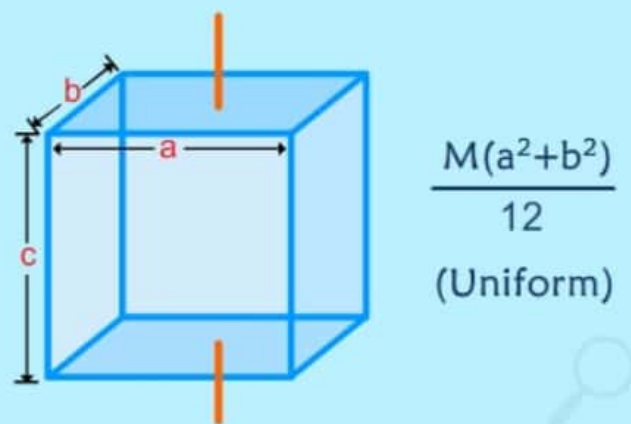
## Rectangular Plate



## Square Plate



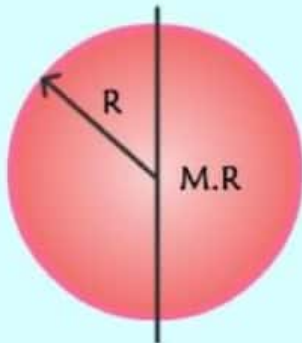
## Cuboid



# MOMENT OF INERTIA

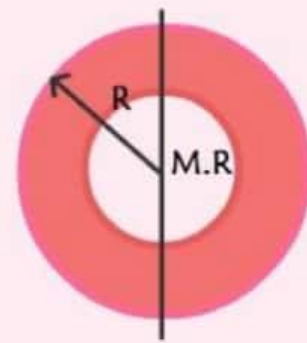
Part II

## Solid Sphere



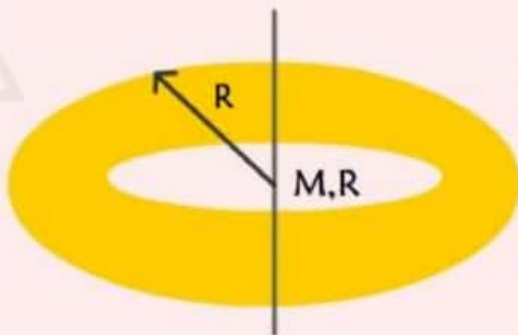
$$I = \frac{2}{5} MR^2 \text{ (Uniform)}$$

## Hollow Sphere



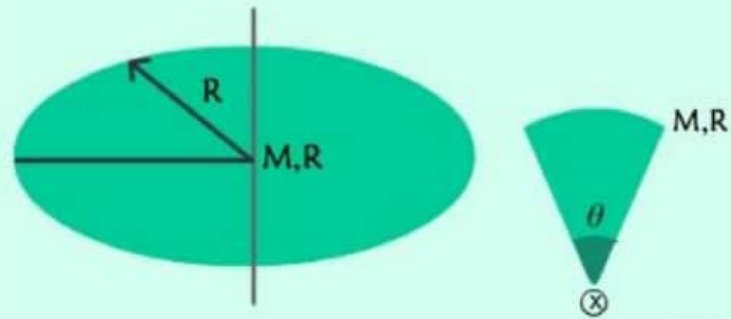
$$I = \frac{2}{3} MR^2 \text{ (Uniform)}$$

## Ring



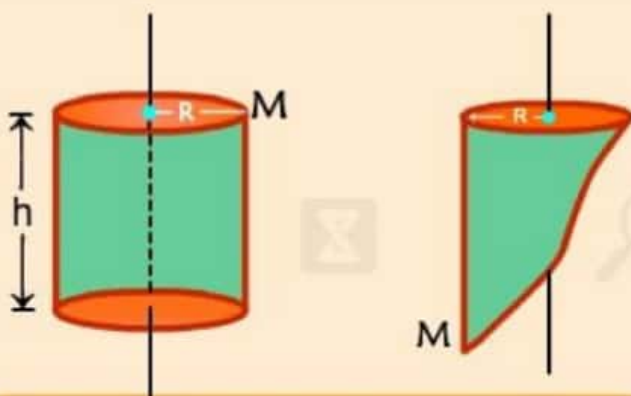
$$I = MR^2 \text{ (Uniform or Non Uniform)}$$

## Disc



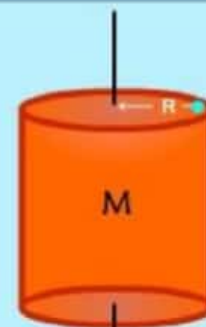
$$I = \frac{MR^2}{2} \text{ (Uniform)}$$

## Hollow cylinder



$$I = MR^2 \text{ (Uniform or Non Uniform)}$$

## Solid cylinder



$$I = \frac{MR^2}{2} \text{ (Uniform)}$$